



A characterization of robust SPR synthesis for systems with l_p parametric uncertainty

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Outline

- Robust SPR with l_p uncertainty: problem statement
- Robust SPR vs. l_p parametric stability margin
- Frequency domain characterization
- Problem solution for the ellipsoidal (l_2) case
- Problem solution for the polyhedral (l_∞ and l_1) case
- Conclusion

Motivation and problem statement

- Robust absolute stability of nonlinear feedback Lur'e systems [Silyak 1969]

- Convergence of recursive identification algorithms [Ljung 1977] and adaptive schemes

Robust SPR problem. Given an uncertain set \mathcal{P} of polynomials, find a polynomial or rational filter $F(s)$ such that

$$\frac{P(s)}{F(s)} \text{ is SPR } \forall P(s) \in \mathcal{P}$$

[Dasgupta et al. 1987], [Anderson et al. 1990]

l_p robust SPR problem

- l_p set of polynomials of degree m

$$\mathcal{P}_p^d := \left\{ P(s) = P_0(s) + \sum_{i=1}^n q_i P_i(s) : \|q\|_p \leq d \right\}$$

$$P_0(s) \in \mathcal{H}; \quad \partial P_0 = m, \quad \partial P_i < m \quad \forall i = 1, \dots, n;$$

$$q = (q_1 \cdots q_n)' \in \mathbb{R}^n; \quad d > 0$$

- Parametric stability margin of the set \mathcal{P}_p^d

$$d^* = \sup_d \mathcal{P}_p^d \supset \mathcal{H}$$

i.e., the maximum l_p norm of the uncertain parameters such that \mathcal{P}_p^d contains only Hurwitz polynomials.

l_p robust SPR problem

Theorem. [Anderson et al. 1990].

Given the set \mathcal{P}_p^d , suppose $p > p^*$. Then, there exist an integer M

and a Hurwitz polynomial $R(s)$ of degree $m + M$ such that the filter

$$F(s) = \frac{R(s)}{(s+1)^M}$$

solves the RSPR problem.

- $F(s)$ can be approximated via a series expansion
 - No closed form for $F(s)$
 - No a-priori knowledge on the degree M of the filter $F(s)$

Characterization of l_p RSPR problem solutions

$$G(s) := \begin{pmatrix} P_1(s) & \dots & P_n(s) \\ P_0(s) & \dots & P_0(s) \end{pmatrix}'$$

$$R(\omega) := \operatorname{Re}[G(j\omega)], \quad I(\omega) := \operatorname{Im}[G(j\omega)].$$

Theorem. All rational filters solving the l_p RSPR are given by

$$F(s) = \frac{\Phi(s)}{P_0(s)}$$

where $\Phi(s)$ is a rational function such that

1. $\Phi(s)$ is SPR;

$$2. \|R(\omega) - \gamma_\Phi(\omega)I(\omega)\|_d > \frac{1}{d} \quad \forall \omega \geq 0$$

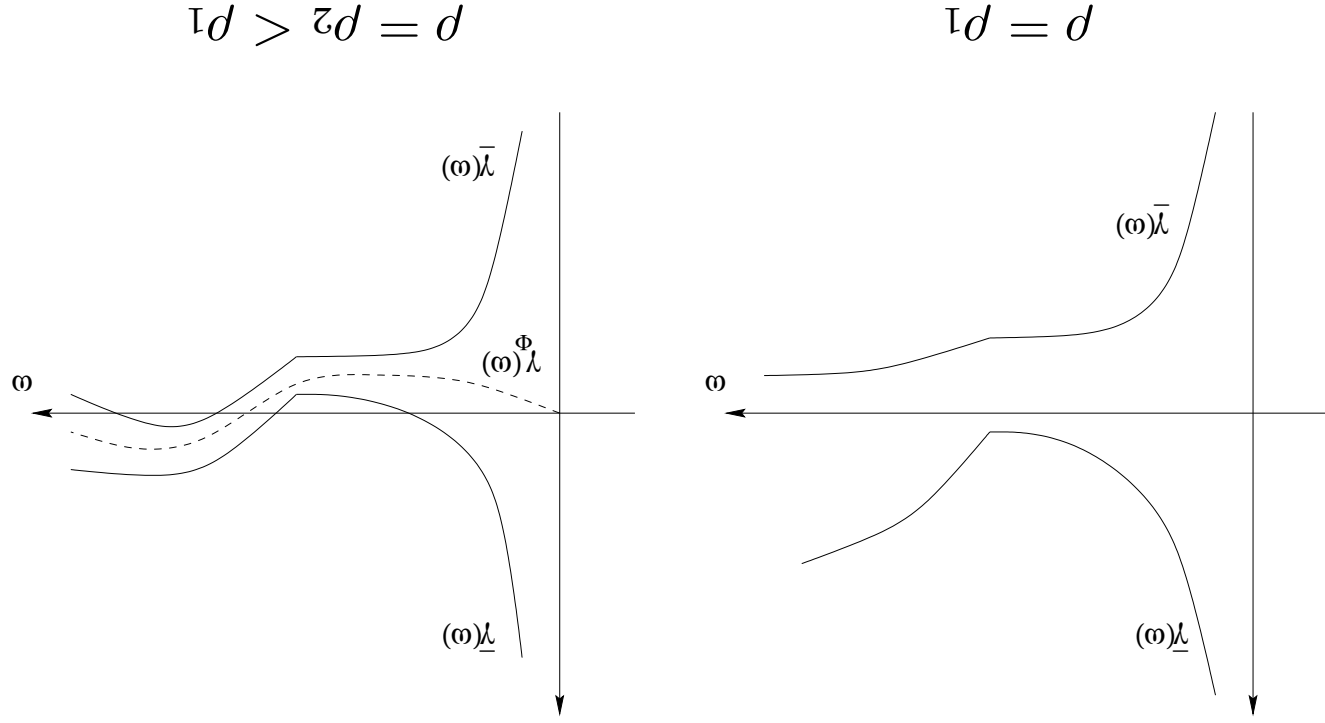
being

$$\gamma_\Phi(\omega) := \operatorname{Im}[\Phi(j\omega)] / \operatorname{Re}[\Phi(j\omega)]; \quad \|\cdot\|_d : \text{dual } d\text{-norm}$$

Characterization of l_p RSPR problem solutions

- Phase condition

$$\|R(\omega) - \gamma_{\Phi} I(\omega)\|_d^d > \frac{d}{1} \Leftrightarrow \underline{\gamma}(\omega) > \gamma_{\Phi}(\omega) > \bar{\gamma}(\omega)$$



l_p RSPR problem solution

- Key. Characterize the set

$$\Gamma_p^d = \left\{ \gamma(\omega) : \|\mathcal{R}(\omega) - \gamma(\omega)I(\omega)\|_p^d > \frac{1}{d} \text{ A } \omega \geq 0 \right\}$$

- A solution exists if and only if a SPR function $\Phi(s)$ can be synthesized such that

$$\gamma_{\Phi}(\omega) \in \Gamma_p^d$$

- Idea. Find a SPR function $\Phi(s)$ such that

$$\gamma_{\Phi}(\omega) \approx \gamma_*(\omega) = \arg \min_{\gamma} \|\mathcal{R}(\omega) - \gamma I(\omega)\|_p^d$$

- $\gamma_*(\omega)$ is independent of p

The ellipsoidal (l_2) case

- If $\rho > \rho_*$, then a positive real (PR) function $\Phi_*(s)$ exists such that

$$\gamma_{\Phi_*}(\omega) = \gamma_*(\omega)$$

- $\Phi_*(s)$ can be explicitly computed in closed form via the solution of a polynomial factorization problem
- The sought function $\Phi(s)$ can be computed by performing a suitable perturbation on $\Phi_*(s)$

The l_2 case

Simplifying assumption (can be relaxed). The set \mathcal{P}_d^p is such that

$$I(\omega) \neq 0 \quad \forall \omega > 0.$$

- The polynomial

$$\Pi(s) = \sum_{i=1}^n P_0(s) P_i(-s) [P_0(-s) P_i(s)]^{\text{odd}}$$

can be factorized as

$$\Pi(s) = A s^r \bar{\Pi}_1(s) \bar{\Pi}_2(-s)$$

with $\bar{\Pi}_1(s)$ and $\bar{\Pi}_2(s)$ monic and Hurwitz.

The l_2 case

- Define

$$\frac{\underline{\Pi}_1(s)}{\underline{\Pi}_2(s)} = \Phi_*^e(s)$$

$$\Phi_*^o(s) = \frac{\underline{\Pi}_1(s)}{\underline{\Pi}_2(s)} s^{\text{sgn}A} (-1)^{(r-1)/2}$$

- $\Phi_*(s)$ is given by

$$\left. \begin{array}{l} \text{odd } r \quad \Phi_*^o(s) \\ \text{even } r \quad \Phi_*^e(s) \end{array} \right\} = \Phi_*(s)$$

The l_2 case

Theorem [Bianchini, Tesi, Vicino 2001]. Assume $\rho < \rho^*$ and $I(\omega) \neq 0 \forall \omega > 0$.

Then, for sufficiently small $\varepsilon, \delta > 0$, the rational function

$$\Phi(s) = \left\{ \begin{array}{l} \Phi_*^e(s)(1 + \delta s)^{\partial \Pi_2 - \partial \Pi_1} \\ \text{for even } r \\ \Phi_*^o(s) \left(\frac{s}{s + \varepsilon} \right)^{\text{sgn} A} (-1)^{(r-1)/2} \cdot (1 + \delta s)^{\partial \Pi_2 - \partial \Pi_1 - \text{sgn} A} (-1)^{(r-1)/2} \\ \text{for odd } r \end{array} \right.$$

- The degree of $F(s)$ is bounded by the degree m of $P(s)$ is such that the filter $F(s) = P_0(s)/\Phi(s)$ solves the l_2 RSPR problem.

The polyhedral (l_∞, l_1) case

- Non-smooth problem and no closed form solution
 - We propose a numerical procedure for the computation of a filter $F(s)$ of given form solving the RSPR problem with guaranteed (possibly maximum) robustness margin $\rho_F \leq \rho^*$.
 - Polynomial filter class of the same degree as $\mathcal{P}_{(\infty,1)}^d$
- $$F(s; \theta) = P_0(s) + \Delta F(s; \theta)$$
- Note. $F(s; 0) = P_0(s)$ is a solution for small ρ
- Whether a polynomial $F(s; \theta)$ solving the RSPR problem exists under the only condition $\rho > \rho^*$ is still an open question.

The l_∞ case

- Uncertain polynomial family of degree n (with independent perturbations)

$$\mathcal{P}_\infty^d := \left\{ P(s) = P_0(s) + \sum_{i=1}^n q_i \hat{a}_i s^{i-1} : \|q\|_\infty \leq d \right\}$$

- Polynomial filter class of degree n

$$F(s; \theta) = P_0(s) + \sum_{i=1}^{n-1} \theta_i s^i$$

$$\theta = (\theta_0, \dots, \theta_{n-1})' \in \mathbb{R}^n$$

The l_∞ case

- Define

$$\Phi(s; \theta) = \frac{P_0(s)}{F(s; \theta)}$$

↑

$$\gamma_\Phi(\omega; \theta) = \frac{\operatorname{Im}[P_0(j\omega)]X^e(\omega; \theta) - \operatorname{Re}[P_0(j\omega)]X^o(\omega; \theta)}{1 + \operatorname{Re}[P_0(j\omega)]X^e(\omega; \theta) + \operatorname{Im}[P_0(j\omega)]X^o(\omega; \theta)}$$

with

$$X^e(\omega; \theta) = \frac{1}{\sum_{i=0, i \text{ even}}^{n-1} \theta_i(j\omega)^i}$$

$$X^o(\omega; \theta) = \frac{1}{\sum_{i=0, i \text{ odd}}^{n-1} \theta_i(j\omega)^i}$$

The l_∞ case

- Let

$$\rho_F(\theta)^{-1} = \sup_{\omega \geq 0} (K_e(\omega) |\operatorname{Re}[P_0(j\omega)] + \gamma_\Phi(\omega; \theta) \operatorname{Im}[P_0(j\omega)]| + K_o(\omega) |\operatorname{Im}[P_0(j\omega)] - \gamma_\Phi(\omega; \theta) \operatorname{Re}[P_0(j\omega)]|)$$

$$+ K_o(\omega) |\operatorname{Im}[P_0(j\omega)] - \gamma_\Phi(\omega; \theta) \operatorname{Re}[P_0(j\omega)]|)$$

with

$$K_e(\omega) = \frac{1}{\sum_{i=0, i \text{ even}}^{n-1} \hat{a}_i \omega^i}, \quad K_o(\omega) = \frac{1}{\sum_{i=0, i \text{ odd}}^{n-1} \hat{a}_i \omega^i}$$

Proposition. The filter $F(s; \theta)$ solves the RSPR problem for all $\rho > \rho_F(\theta)$ provided that θ belongs to the set

$$\Theta_{\Phi^+} = \left\{ \theta \in \mathbb{R}^n : \inf_{\omega \geq 0} [1 + \operatorname{Re}[P_0(j\omega)] X_e(\omega; \theta) + \operatorname{Im}[P_0(j\omega)] X_o(\omega; \theta)] > 0 \right\}$$

The l_∞ case

- The maximum perturbation norm $\rho_F(\theta)$ for which the filter $F(s; \theta)$ solves the RSPR problem can be maximized through the solution of the non-convex optimization problem

$$\theta_* = \arg \sup_{\theta \in \Theta^+} \rho_F(\theta)$$

- $\rho_F(\theta_*)$ is a lower bound to the maximum $\rho \leq \rho_*$ for which a polynomial solution exists
- A performance measure of the filter $F(s; \theta_*)$ is given by the comparison of $\rho_F(\theta_*)$ and ρ_*

The l_1 case

- Uncertain polynomial family

$$\mathcal{P}_d^1 := \left\{ P(s) = P_0(s) + \sum_n^{i=1} q_i \hat{a}_i s^{i-1} : \|q\|_1 \leq d \right\}$$

- Polynomial filter class

$$F(s; \theta) = P_0(s) + \sum_{i=1}^{n-1} \theta_i s^i$$

$$\theta = (\theta_0, \dots, \theta_{n-1})' \in \mathbb{R}^n$$

The l_1 case

- Robustness margin of $F(s; \theta)$

$$\rho_F(\theta)^{-1} = \sup_{\omega \geq 0} \max_{i=0, \dots, n-1} J_i(\gamma_\Phi(\omega; \theta), \omega)$$

where

$$J_i(\gamma, \omega) = \begin{cases} \frac{|a_i|\omega^i |\operatorname{Re}[P_0(j\omega)] + \gamma \operatorname{Im}[P_0(j\omega)]|}{|P_0(j\omega)|^2} & i \text{ even} \\ \frac{|a_i|\omega^i |\operatorname{Im}[P_0(j\omega)] - \gamma \operatorname{Re}[P_0(j\omega)]|}{|P_0(j\omega)|^2} & i \text{ odd.} \end{cases}$$

- A filter $F(s; \theta^*)$ with guaranteed robustness margin $\rho_F(\theta^*)$ is obtained through the solution of the optimization problem

$$\theta^* = \arg \sup_{\theta \in \Theta^+} \rho_F(\theta)$$

Polyhedral uncertainty: odd (even) perturbations

- Assume only the odd (even) coefficients of the polynomial $P(s)$ are perturbed, i.e., consider the uncertain set

$$\mathcal{P}_{(\infty,1),e}^d = \left\{ P(s) \in \mathcal{P}_{(\infty,1)}^d : \hat{a}_i = 0, \quad i \text{ even} \right\}$$

OR

$$\mathcal{P}_{(\infty,1),o}^d = \left\{ P(s) \in \mathcal{P}_{(\infty,1)}^d : \hat{a}_i = 0, \quad i \text{ odd} \right\}$$

- The proposed characterization yields a polynomial filter of degree n which is a solution of the RSPR problem for all $p > p^*$

Polyhedral uncertainty: odd (even) perturbations

Theorem. Let $p > p^*$. Then, the RSPR problem for the uncertain set $\mathcal{P}_{(\infty,1),e}^p$ (resp. $\mathcal{P}_{(\infty,1),o}^p$) is solved by the polynomial filter $F_e(s)$ (resp. $F_o(s)$) of degree n given by

$$F_e(s) = \prod_{e=1}^{e_n} (s^2 + 2\zeta\omega_{e,i}s + \omega_{e,i}^2)(1 + \delta s)^{n \bmod 2}$$

$$F_o(s) = (s + \varepsilon) \prod_{o=1}^{o_{n-1}} (s^2 + 2\zeta\omega_{o,i}s + \omega_{o,i}^2)(1 + \delta s)^{(n-1) \bmod 2}$$

where ζ, δ are sufficiently small scalars, and

$$\Omega_o^e = \{\omega_{e,1}, \dots, \omega_{e,e_n}\}, \quad \Omega_o^o = \{0, \omega_{o,1}, \dots, \omega_{o,e_{n-1}}\}$$

are the sets of frequencies at which $\operatorname{Re}[P_0(j\omega)] = 0$ (resp. $\operatorname{Im}[P_0(j\omega)] = 0$).

Conclusion

- Complete frequency domain characterization of the solutions of the robust SPR problem for l_p uncertain polynomial sets
- The proposed characterization yields synthesis methods for the ellipsoidal (l_2) and the polyhedral (l_∞, l_1) case
- The filter output by the above methods has degree bounded by the degree of the uncertain polynomial
- Closed-form rational solution in the ellipsoidal case
- Numerical procedure for the synthesis of polynomial filters with guaranteed robustness margin in the polyhedral case.